

Merging of equivalent reflections

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Two steps are required to merge equivalent reflections with the `cctbx`. Given a `miller.array` `m`,

1. `m1 = m.map_to_asu()` projects each Miller index into the asymmetric unit, i.e. for each group of equivalent reflection, each index of that group is replaced by the same Miller index;
2. `merging = m1.merge_equivalents()` finds the group of identical Miller indices, gathers the data and sigma's for each group in turn, computes an average datum and an associated sigma; `merging.array()` is then the `miller.array` containing those unique indices associated to those averaged data and sigma.

The first step is only about space-group algebra whereas the second step is only about statistics and this division is therefore optimally orthogonal in a sense. We will now expound each step, starting from the second one.

1 Averaging of equivalent reflections

Given n data y_1, \dots, y_n and the associated estimated standard deviations $\sigma_1, \dots, \sigma_n$, either the amplitudes or the intensities for a group of symmetry equivalent reflections, we sought to combine those data and sigma's into a single datum and an associated standard deviation.

That merged amplitude or intensity \bar{y} is computed as a weighted average of the $\{y_i\}_{i=1, \dots, n}$,

$$\bar{y} = \frac{\sum_{i=1}^n w_i y_i}{\sum_{i=1}^n w_i}. \quad (1)$$

There are two ways to handle this from a statistical point of view.

1.1 External variance

The first one gives a mathematical meaning to the loose assertion that all y_i should be equal within the uncertainties quantified by the σ_i (the exact equality is required by those being equivalent reflections but this is spoiled by all sources of errors in measurement

and data processing up to this point). Each y_i is then seen as an outcome of a random variable \hat{y}_i which is an unbiased estimator for the value y_{eq} that all equivalent reflections should ideally share, i.e. mathematically

$$\begin{aligned} E(\hat{y}_i) &= y_{\text{eq}}, \quad \forall i = 1, \dots, n \\ V(\hat{y}_i) &= \sigma_i^2. \end{aligned} \quad (2)$$

Then the average \bar{y} is the outcome of the random variable

$$\hat{y} = \frac{\sum_{i=1}^n w_i \hat{y}_i}{\sum_{i=1}^n w_i}. \quad (3)$$

which is obviously an unbiased estimator of y_{eq} (i.e. $E(\hat{y}) = y_{\text{eq}}$). If we postulate that the measurement and data reduction lead to uncorrelated \hat{y}_i , then

$$V(\hat{y}) = \sum_{i=1}^n \omega_i^2 V(\hat{y}_i) \quad (4)$$

where

$$\omega_i = \frac{w_i}{\sum_{i=1}^n w_i}. \quad (5)$$

This is often called the “external” variance. Its lowest possible value is obtained for the weights

$$\tilde{w}_i = \frac{1}{V(\hat{y}_i)} = \frac{1}{\sigma_i^2}, \quad (6)$$

as well as for any weights differing from those by a common proportionality factor, as demonstrated in appendix A and this minimum is equal to

$$V(\hat{y}) = \frac{1}{\sum_{i=1}^n \tilde{w}_i} = \frac{1}{n \langle \tilde{w}_i \rangle}. \quad (7)$$

Those are the weights and the external variance used by the `cctbx`.

This is not the only popular choice. Indeed ShelXL [?] uses instead

$$w_i = \begin{cases} \frac{y_i}{\sigma_i^2} & \text{if } \frac{y_i}{\sigma_i} > 3, \\ \frac{3}{\sigma_i} & \text{otherwise.} \end{cases} \quad (8)$$

1.2 Internal variance

The second way to handle the average (1) is to consider it as a mere sample mean, but a weighted one, ignoring the special property of the y_i . Those data are considered as the outcome of a sample (Y_1, \dots, Y_n) of a random variable Y , and \bar{y} is then the outcome of the unbiased estimator of $E(Y)$,

$$\bar{Y} = \frac{\sum_{i=1}^n w_i Y_i}{\sum_{i=1}^n w_i}. \quad (9)$$

It is then natural to also compute a weighted sample variance

$$S^2 = \frac{\sum_{i=1}^n w_i (Y_i - \bar{Y})^2}{\sum_{i=1}^n w_i}. \quad (10)$$

However, it is a biased estimator of $V(Y)$, as it is well-known in the unweighted case, i.e. all weights w_i equal. The unbiased estimator

$$S_{n-1}^2 = \frac{S^2}{1 - \sum_{i=1}^n \omega_i^2} \quad (11)$$

$$= \frac{\sum_{i=1}^n w_i}{(\sum_{i=1}^n w_i)^2 - \sum_{i=1}^n w_i^2} \sum_{i=1}^n w_i (Y_i - \bar{Y})^2 \quad (12)$$

is therefore preferred. Those variances are called “internal” as opposed to the variance we have previously discussed. The `cctbx` computes it by using an instance of `scitbx::mean_and_variance` and calling its member function `gsl_stats_wvariance` whose implementation and naming follows the function with the same name in the GNU Scientific Library [?]. Since this formula is not that easily found in textbooks, we demonstrate it in appendix B.

Finally, it is customary to estimate the variance associated with \bar{y} by taking the greatest of the internal and external variance. That is what the `cctbx` does as well as `ShelXL`.

Appendix A Minimum variance weights

We will demonstrate eqn (6). We seek the solution of the constrained minimisation problem

$$\min V(\hat{y}), \quad (13)$$

$$V(\hat{y}) = \sum_{i=1}^n \omega_i^2 V(\hat{y}_i), \quad (14)$$

$$\sum_{i=1}^n \omega_i = 1. \quad (15)$$

We can solve it by minimising the Lagrangian

$$L = V(\hat{y}) - \lambda \sum_{i=1}^n \omega_i, \quad (16)$$

$$= \sum_{i=1}^n \left[V(\hat{y}_i) \left(\omega_i - \frac{\lambda}{2V(\hat{y}_i)} \right)^2 - \frac{\lambda^2}{4V(\hat{y}_i)} \right] \quad (17)$$

Thus L reaches its minimum at

$$\omega_i = \frac{\lambda}{2V(\hat{y}_i)} \quad (18)$$

and using eqn (15), it comes

$$\frac{\lambda}{2} = \frac{1}{\sum_{i=1}^n \frac{1}{V(\hat{y}_i)}} \quad (19)$$

and therefore the minimum is reached at

$$\omega_i = \frac{\frac{1}{V(\hat{y}_i)}}{\sum_{j=1}^n \frac{1}{V(\hat{y}_j)}}. \quad (20)$$

That demonstrates eqn (6) and since weights differing by a common proportionality factor yield the same ω_i , QED.

Appendix B Weighted sample variance

First let us remember that, by definition of a sample,

$$E(Y_i) = E(Y), \quad \forall i = 1, \dots, n \quad (21)$$

$$V(Y_i) = V(Y) \quad (22)$$

Therefore,

$$\begin{aligned} V(Y) &= \sum_{i=1}^n \omega_i V(Y_i) \\ &= E \left[\sum_{i=1}^n \omega_i (Y_i - E(Y))^2 \right] \\ &= E \left[\sum_{i=1}^n \omega_i (Y_i - \bar{Y})^2 \right] + 2E \left[\sum_{i=1}^n \omega_i (Y_i - \bar{Y})(\bar{Y} - E(Y)) \right] + \sum_{i=1}^n \omega_i E[(\bar{Y} - E(Y))^2] \end{aligned}$$

Then,

- since $E(\bar{Y}) = E(Y)$, the last term is $V(\bar{Y})$;
- by definition of \bar{Y} , $\sum_{i=1}^n \omega_i (Y_i - \bar{Y}) = 0$ and the second term is therefore 0.

Thus

$$V(Y) = E(S^2) + V(\bar{Y}). \quad (23)$$

But

$$V(\bar{Y}) = \sum_{i=1}^n \omega_i^2 V(Y) \quad (24)$$

and therefore

$$V(Y) = \frac{E(S^2)}{1 - \sum_{i=1}^n \omega_i^2} \quad (25)$$